Exhibit R-2, RDT&E Budget Item Justification: PB 2019 Navy

Date: February 2018

Appropriation/Budget Activity

R-1 Program Element (Number/Name)

1319: Research, Development, Test & Evaluation, Navy I BA 4: Advanced

PE 0604031N I Large Unmanned Undersea Vehicles

Component Development & Prototypes (ACD&P)

COST (\$ in Millions)	Prior Years	FY 2017	FY 2018	FY 2019 Base	FY 2019 OCO	FY 2019 Total	FY 2020	FY 2021	FY 2022	FY 2023	Cost To Complete	Total Cost
Total Program Element	0.000	0.000	0.000	92.613	-	92.613	135.641	136.136	121.836	129.429	Continuing	Continuing
2094: Unmanned Underwater Vehicle	0.000	0.000	0.000	92.613	-	92.613	135.641	136.136	121.836	129.429	Continuing	Continuing

Note

FY 2018 and prior funding in Program Element (PE) 0603502N. Project realigned from PE 0603502N starting in FY 2019.

A. Mission Description and Budget Item Justification

The Snakehead Large Displacement Unmanned Undersea Vehicle (LDUUV) is the Navy's Large Displacement UUV effort as part of the UUV Family of Systems (FOS). It is the number one Submarine-launched UUV priority due to the additional endurance and capability it will bring to the fleet in support of maintaining the Navy's undersea superiority. In order to accelerate future capability and support steady growth of the fleet's UUV FoS the Snakehead LDUUV program will design and build a modular, reconfigurable Unmanned Undersea Vehicle (UUV) with Open Architecture (OA) software (SW) focused on introducing a new class (large displacement) of UUVs to the Navy to provide increased endurance, payload hosting, and delivery capability.

The Snakehead LDUUV will be modular in design and include hotel functionality (guidance and control, navigation, autonomy, situational awareness, core communications, and power distribution), energy and power, propulsion and maneuvering, mission sensors, and communications links. It is intended that modules will have well defined interfaces for the purposes of implementing cost-effective upgrades in future increments to leverage advances in technology. The Snakehead LDUUV is a CNO/ASN(RDA) approved Accelerated Acquisition phased approach to build capabilities at a manageable level of risk in the Navy's class of Large Displacement Unmanned Undersea Vehicles. It currently consists of two phases of government-led development with significant industry involvement transitioning to industry production of the full vehicles.

B. Program Change Summary (\$ in Millions)	FY 2017	FY 2018	FY 2019 Base	FY 2019 OCO	FY 2019 Total
Previous President's Budget	0.000	0.000	0.000	-	0.000
Current President's Budget	0.000	0.000	92.613	-	92.613
Total Adjustments	0.000	0.000	92.613	-	92.613
 Congressional General Reductions 	-	-			
 Congressional Directed Reductions 	-	-			
 Congressional Rescissions 	-	-			
 Congressional Adds 	-	-			
 Congressional Directed Transfers 	-	-			
 Reprogrammings 	-	-			
SBIR/STTR Transfer	-	-			
Rate/Misc Adjustments	0.000	0.000	92.613	-	92.613

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Exhibit R-2, RDT&E Budget Item Justification: PB 2019 Navy		Date: February 2018
Appropriation/Budget Activity 1319: Research, Development, Test & Evaluation, Navy I BA 4: Advanced Component Development & Prototypes (ACD&P)	R-1 Program Element (Number/Name) PE 0604031N / Large Unmanned Undersea Vehicles	
Change Summary Explanation Program Changes: FY19 +\$92,613K realigned from 0603502N, Project Technical: Not applicable. Schedule: Not applicable.	ot 2094.	

PE 0604031N: Large Unmanned Undersea Vehicles Navy

Exhibit R-2A, RDT&E Project Ju		Date: Febr	uary 2018									
Appropriation/Budget Activity 1319 / 4		, , , , ,						umber/Name) nanned Underwater Vehicle				
COST (\$ in Millions)	COST (\$ in Millions) Prior Years FY 2017 FY 2018 Ba				FY 2019 OCO	FY 2019 Total	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cost	
2094: Unmanned Underwater Vehicle	0.000	0.000	0.000	92.613	-	92.613	135.641	136.136	121.836	129.429	Continuing	Continuing
Quantity of RDT&E Articles		-	-	-	-	-	-	-	-	-		

Note

FY 2018 and prior funding in Program Element (PE) 0603502N. Project moved from PE 0603502N starting in FY 2019.

A. Mission Description and Budget Item Justification

In order to accelerate future capability and support steady growth of the fleet's UUV Family of Systems (FoS) the Snakehead Large Displacement Unmanned Undersea Vehicle (LDUUV) program will design and build a modular, reconfigurable Unmanned Undersea Vehicle (UUV) with Open Architecture (OA) software (SW) focused on introducing a new class (large displacement) of UUVs to the Navy to provide increased endurance, payload hosting, and delivery capability.

The Snakehead LDUUV will be modular in design and include hotel functionality (quidance and control, navigation, autonomy, situational awareness, core

The Snakehead LDUUV will be modular in design and include hotel functionality (guidance and control, navigation, autonomy, situational awareness, core communications, and power distribution), energy and power, propulsion and maneuvering, mission sensors, and communications links. It is intended that modules will have well defined interfaces for the purposes of implementing cost-effective upgrades in future increments to leverage advances in technology. The Snakehead LDUUV is a CNO/ASN(RDA) approved Accelerated Acquisition phased approach to build capabilities at a manageable level of risk in the Navy's class of Large Displacement Unmanned Undersea Vehicles. It consists of two phases of government-led development with significant industry involvement transitioning to industry production of the full vehicles.

B. Accomplishments/Planned Programs (\$ in Millions, Article Quantities in Each)			FY 2019	FY 2019	FY 2019
	FY 2017	FY 2018	Base	oco	Total
Title: LDUUV Product Development	0.000	0.000	81.695	0.000	81.695
Articles:	-	-	-	-	-
FY 2018 Plans:					
FY 2018 funding in Program Element (PE) 0603502N.					
FY 2019 Base Plans:					
Complete detailed design for Phase I LDUUV and complete Critical Design Review (CDR) in 1QFY19.					
Procure remaining materials and parts and commence fabrication of two (2) Phase I LDUUVs. Develop data					
products and					
analysis for submarine and surface ship integration. Route technical data package for platform integration and adjudicate technical review.					

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Exhibit R-2A, RDT&E Project Justification: PB 2019 Navy				Date: Febr	uary 2018		
1319 / 4 PE	Program Element (Number/I 0604031N <i>I Large Unmanned</i> nicles			ect (Number/Name) I Unmanned Underwater Vehicle			
B. Accomplishments/Planned Programs (\$ in Millions, Article Quantities in Ea	<u>ch)</u>	FY 2017	FY 2018	FY 2019 Base	FY 2019 OCO	FY 2019 Total	
Provide engineering services for initial subsystem testing and risk reduction demos.							
FY 2019 OCO Plans: N/A							
FY 2018 to FY 2019 Increase/Decrease Statement: FY 2018 funding in Program Element (PE) 0603502N. FY 2019 increase in funding efforts.	supports detailed design						
Title: LDUUV Support		0.000	0.000	8.930	0.000	8.93	
	Articles:	-	-	-	-	-	
FY 2018 Plans: FY 2018 funding in Program Element (PE) 0603502N.							
FY 2019 Base Plans: Complete final design documentation and drawings, submarine Interface Control Dottest plans to assemble baseline technical data package for platform integration. Support fabricat	•						
Support platform integration efforts. Continue supportability analysis.							
Support Fleet with demonstration exercises with demo vehicles to develop Tactics,	Techniques, and Procedures.						
FY 2019 OCO Plans: N/A							
FY 2018 to FY 2019 Increase/Decrease Statement: FY 2018 funding in Program Element (PE) 0603502N. FY 2019 increase due to add design efforts.	litional support for detailed						
Title: LDUUV Management	Articles:	0.000	0.000	1.988 -	0.000	1.988	
FY 2018 Plans:							
FY 2018 funding in Program Element (PE) 0603502N.							
FY 2019 Base Plans:							

PE 0604031N: Large Unmanned Undersea Vehicles Navy

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Exhibit R-2A, RDT&E Project Justification: PB 2019 Navy			Date: February 2018
, · · · · · · · · · · · · · · · · · · ·	R-1 Program Element (Number/Name) PE 0604031N / Large Unmanned Undersea Vehicles	• `	umber/Name) nanned Underwater Vehicle

B. Accomplishments/Planned Programs (\$ in Millions, Article Quantities in Each)	FY 2017	FY 2018	FY 2019 Base	FY 2019 OCO	FY 2019 Total
Provide program management support and travel for the LDUUV program. Program management plans include overall technical guidance and leadership for the program. Oversight of financial and logistics efforts and coordination with Navy and other DoD organizations and contractors as required to ensure successful execution of the program.					
FY 2019 OCO Plans: N/A					
FY 2018 to FY 2019 Increase/Decrease Statement: FY 2018 funding in Program Element (PE) 0603502N. FY 2019 increase supports management of detailed design efforts.					
Accomplishments/Planned Programs Subtotals	0.000	0.000	92.613	0.000	92.613

C. Other Program Funding Summary (\$ in Millions)

			FY 2019	FY 2019	FY 2019					Cost Io	
<u>Line Item</u>	FY 2017	FY 2018	Base	OCO	Total	FY 2020	FY 2021	FY 2022	FY 2023	Complete	Total Cost
 RDTEN/0603502N/2094: 	21.945	60.187	0.000	-	0.000	0.000	0.000	0.000	0.000	0.000	146.992
Llamana and Llandamustanu Valaiala											

Unmanned Underwater Vehicle

Remarks

Funding moved to new Program Element in FY2019

D. Acquisition Strategy

Utilizing Navy requirements to insert incremental capability, the LDUUV program will design, build, and test risk-reducing UUVs in two phases followed by competitive award of a production contract.

E. Performance Metrics

LDUUV - Complete Critical Design Review (CDR) 1Q FY19

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Exhibit R-3, RDT&E Project Cost Analysis: PB 2019 Navy

Appropriation/Budget Activity

1319 / 4

R-1 Program Element (Number/Name)
PE 0604031N / Large Unmanned Undersea Vehicles

Project (Number/Name)
2094 / Unmanned Underwater Vehicle

Product Developmen	nt (\$ in M	illions)		FY 2	2017	FY 2	018	FY 2 Ba	2019 ase	FY 2		FY 2019 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To	Total Cost	Target Value of Contract
LDUUV Vehicles, Hardware, & Design	WR	NUWC Newport : Newport, RI	0.000	0.000		0.000		12.090	Dec 2018	-		12.090	Continuing	Continuing	Continuing
LDUUV Vehicles, Hardware, & Design	C/CPFF	Various : Various	0.000	0.000		0.000		46.258	Dec 2018	-		46.258	Continuing	Continuing	Continuing
LDUUV Vehicles, Hardware, & Design	WR	NSWC Carderock : West Bethesda, MD	0.000	0.000		0.000		3.254	Dec 2018	-		3.254	Continuing	Continuing	Continuinç
LDUUV Vehicles, Hardware, & Design	WR	NSWC Panama City : Panama City, FL	0.000	0.000		0.000		0.200	Dec 2018	-		0.200	Continuing	Continuing	Continuinç
LDUUV Vehicles, Hardware, & Design	SS/CPFF	ARL PSU : Statte College, PA	0.000	0.000		0.000		5.997	Dec 2018	-		5.997	Continuing	Continuing	Continuinç
LDUUV Vehicles, Hardware, & Design	WR	SSC Pacific : San Diego, CA	0.000	0.000		0.000		0.495	Jan 2019	-		0.495	Continuing	Continuing	Continuing
LDUUV Vehicles, Hardware, & Design	WR	NUWC Keyport : Keyport, WA	0.000	0.000		0.000		4.887	Jan 2019	-		4.887	Continuing	Continuing	Continuinç
LDUUV Risk Reduction Soanr	SS/CPFF	ARL UT : Austin, TX	0.000	0.000		0.000		0.647	Feb 2019	-		0.647	Continuing	Continuing	Continuinç
LDUUV Expirimentation and Risk Reduction - Battery Certification	WR	NSWC Crane : Crane, IN	0.000	0.000		0.000		1.000	Dec 2018	-		1.000	Continuing	Continuing	Continuinç
LDUUV Platform Integration	Various	Various : Various	0.000	0.000		0.000		6.867	Dec 2018	-		6.867	Continuing	Continuing	Continuing
		Subtotal	0.000	0.000		0.000		81.695		-		81.695	Continuing	Continuing	N/A

Remarks

FY 2018 and prior funding in Program Element (PE) 0603502N.

PE 0604031N: Large Unmanned Undersea Vehicles Navy

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Exhibit R-3, RDT&E Project Cost Analysis: PB 2019 Navy Date: February 2018

Appropriation/Budget Activity

1319 / 4

R-1 Program Element (Number/Name) PE 0604031N I Large Unmanned Undersea 2094 I Unmanned Underwater Vehicle Vehicles

Project (Number/Name)

Support (\$ in Million	Support (\$ in Millions)			FY 2	2017	FY 2	018	FY 2 Ba	2019 ise	FY 2		FY 2019 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To	Total Cost	Target Value of Contract
LDUUV Engineering Support	WR	NUWC Newport : Newport, RI	0.000	0.000		0.000		3.390	Dec 2018	-		3.390	Continuing	Continuing	Continuing
LDUUV Launch and Recovery Engineering Support	WR	NSWC Panama City : Panama City, FL	0.000	0.000		0.000		0.510	Feb 2019	-		0.510	Continuing	Continuing	Continuing
LDUUV Hydrodynamics and Propulsion Engineering Support	C/CPFF	Various : Various	0.000	0.000		0.000		1.088	Dec 2018	-		1.088	Continuing	Continuing	Continuing
LDUUV Command and Control Engineering Support	WR	NSWC Carderock : West Bethsda, MD	0.000	0.000		0.000		1.505	Dec 2018	-		1.505	Continuing	Continuing	Continuing
LDUUV Engineering	WR	SSC Pacific : San Diego, CA	0.000	0.000		0.000		0.468	Dec 2018	-		0.468	Continuing	Continuing	Continuing
Need Item Text	SS/CPFF	APL/JHU : Laurel, MD	0.000	0.000		0.000		0.469	Jan 2019	-		0.469	Continuing	Continuing	Continuing
Need Item Text	WR	NUWC Keyport : Keyport, WA	0.000	0.000		0.000		0.750	Dec 2018	-		0.750	Continuing	Continuing	Continuing
Need Item Text	SS/CPFF	Various : Various	0.000	0.000		0.000		0.750	Feb 2019	-		0.750	Continuing	Continuing	Continuing
	•	Subtotal	0.000	0.000		0.000		8.930		-		8.930	Continuing	Continuing	N/A

Remarks

FY 2018 and prior funding in Program Element (PE) 0603502N.

Management Servic	Management Services (\$ in Millions)			FY 2017		FY 2018		FY 2019 Base		FY 2019 OCO					
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To	Total Cost	Target Value of Contract
LDUUV Program Management	C/BA	NUWC Newport : Newport, RI	0.000	0.000		0.000		0.698	Dec 2018	-		0.698	Continuing	Continuing	Continuing
LDUUV Program Management	Various	Various : Various	0.000	0.000		0.000		1.115	Dec 2018	-		1.115	Continuing	Continuing	Continuing

PE 0604031N: Large Unmanned Undersea Vehicles Navy

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Exhibit K-3, KDT&E Project Cost Analysis. 1 B 2019 Navy	Date. I ebidary 2010
Exhibit R-3, RDT&E Project Cost Analysis: PB 2019 Navy	Date: February 2018

Appropriation/Budget Activity R-1 Program Element (Number/Name) Project (Number/Name) 1319 *l* 4

PE 0604031N I Large Unmanned Undersea 2094 I Unmanned Underwater Vehicle Vehicles

Management Service	es (\$ in M	illions)		FY 2	2017	FY 2	2018	FY 2 Ba		FY 2	2019 CO	FY 2019 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To	Total Cost	Target Value of Contract
LDUUV Travel	Various	NAVSEA : Washington, DC	0.000	0.000		0.000		0.175	Dec 2018	-		0.175	Continuing	Continuing	Continuing
		Subtotal	0.000	0.000		0.000		1.988		-		1.988	Continuing	Continuing	N/A

Remarks

FY 2018 and prior funding in Program Element (PE) 0603502N.

	Prior Years	FY 2	2017	FY 2	018	FY 2 Ba	019 se	FY 2	FY 2019 Total	Cost To	Total Cost	Target Value of Contract
Project Cost Totals	0.000	0.000		0.000		92.613		-	92.613	Continuing	Continuing	N/A

Remarks

FY 2018 and prior funding in Program Element (PE) 0603502N.

PE 0604031N: Large Unmanned Undersea Vehicles Navy

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thibit R-4, RDT&E Schedule Pr		ГЪ	20 T	9 ма	vy																	Da	ate:	Feb	ruar	y 201	18
Appropriation/Budget Activity 1319 / 4										R-1 Program Element (Number/Name) PE 0604031N / Large Unmanned Undersea Vehicles Project (Number/Name) 2094 / Unmanned Underwater Vehicles																	
-DUUV	FY 2017 FY 2018 FY 20										019 FY 2020 FY 2021								1	FY 2022 FY 2023							
	10	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q 2	Q 30	Q 4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q
Project Unit Moved from Prograr Element 0603502									New PE																		
DUUV Development	-j	1	1	<u> </u>	İ	İ		T	i	Tj-	i	1	İ	İ						İ	İ	İ	1	<u> </u>	İ		
Experimentation Risk Reduction	n									E	xperi	ment	ation	n Ris	k Redu	ction	and	TRI	Matur	atio	n						
Design Reviews	\dashv	╁	†	┧─	╁	<u> </u>		T		\neg	$\neg \neg$	7	1					$\overline{ }$			7		$\overline{}$]_	 		\neg
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Phase 1	_i_	┪	┪	<u> </u>	i –	İ	İ	T	i	_ _	┪	†	j —	İ				İ		i –	i —	İ	†	j —	İ	İ	一
Detailed Design (continued from P 0603502N									Detail Design																		
Long Lead Material & Fabrication	nİ	İ	İ	İ	İ		İİ	j	L	L Mat	t. & F	ab	_	İ				İİ		İ	İ	İ	İ	İ	İ	İİ	İ
System Integration & Tes	st	ĺ	ĺ	İ	ĺ	İ		ĺ			l I	ntegr	atior	n and	l Test			İİ		ĺ	İ	ĺ	İ	ĺ	İ	İİ	j
Military Utility Assessment (MUA Testin		İ	İ	İ	İ			İ	j	İ						F	Phas	e 1 N	MUA	İ	İ	İ	İ	İ	İ		İ
Phase 2	1	1	1	1				T			1	1								İ	1						
Preliminary and Detail Desig	n												Pre	elim I	Design	ı	Deta	il De	sign		l						
Long Lead Material and Fabricatio	n	İ	İ	İ	İ		İ	İ	j	İ	İ	İ					Lon	ng Le	ad Mat	teria	i&F	abrio	catio	n			İ
System Integration and Tes	st																								Inte	eg &	Гest
DUUV (INPs)	<u> </u>	Ţ	İ	Ţ	İ	İ		T	j	Tj-	İ	İ	j —	İ				İ		İ	İ	İ	İ	j —	İ		i
Fleet Familiarization Training an Exercise									Tact	tics, 7	echn	iques	s, Pr	oced	ures (T	TPs)) and	CO	NOP D	eve	loper	ment	t				
019PB - 0604031N - 2094																											

Exhibit R-4A, RDT&E Schedule Details: PB 2019 Navy		Date: February 2018
Appropriation/Budget Activity 1319 / 4	R-1 Program Element (Number/Name) PE 0604031N / Large Unmanned Undersea Vehicles	umber/Name) manned Underwater Vehicle

Schedule Details

	St	art	E	nd		
Events by Sub Project	Quarter	Year	Quarter	Year		
LDUUV						
Project Unit Moved from Program Element 0603502N:	1	2019	1	2019		
LDUUV Development: Experimentation Risk Reduction:	1	2019	4	2022		
Design Reviews: Phase 1 CDR	1	2019	1	2019		
Design Reviews: Phase 2 PDR	4	2020	4	2020		
Design Reviews: Phase 2 CDR	4	2021	4	2021		
Phase 1: Detailed Design (continued from PE 0603502N):	1	2019	2	2019		
Phase 1: Long Lead Material & Fabrication:	1	2019	2	2020		
Phase 1: System Integration & Test:	4	2019	4	2020		
Phase 1: Military Utility Assessment (MUA) Testing:	1	2021	4	2021		
Phase 2: Preliminary and Detail Design: Prelminary Design	2	2020	4	2020		
Phase 2: Preliminary and Detail Design:	1	2021	4	2021		
Phase 2: Long Lead Material and Fabrication:	4	2020	3	2023		
Phase 2: System Integration and Test:	2	2023	4	2023		
LDUUV (INPs): Fleet Familiarization Training and Exercises:	1	2019	4	2022		