Exhibit R-2, RDT&E Budget Item Justification: FY 2018 Army

Date: May 2017

Appropriation/Budget Activity

R-1 Program Element (Number/Name)

2040: Research, Development, Test & Evaluation, Army I BA 4: Advanced

PE 0604017A I Robotics Development

Component Development & Prototypes (ACD&P)

COST (\$ in Millions)	Prior Years	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total	FY 2019	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cost
Total Program Element	-	0.000	0.000	39.608	-	39.608	69.070	16.728	17.254	7.251	Continuing	Continuing
FD2: Soldier Robotics Systems	-	0.000	0.000	1.512	-	1.512	2.812	3.728	4.254	4.251	0.000	16.557
FD3: Battery Modernization & Interface Standardization	-	0.000	0.000	0.847	-	0.847	0.858	0.000	0.000	0.000	0.000	1.705
FD9: Robotics Systems	-	0.000	0.000	37.249	-	37.249	65.400	13.000	13.000	3.000	Continuing	Continuing

Note

Army

In FY2018 funding for Unmanned Ground Vehicles (UGV) Robotics Development (RD) transitions from PE 0604641A Tactical Unmanned Ground Vehicle, Project DV7 Small Unmanned Ground Vehicle to PE 0604017A Robotics Development, Project FD2 Soldier Robotics Systems, and funding for Applique and Large Unmanned Ground Systems (ALUGS) Robotics Development (RD) transitions from PE 0604641A Tactical Unmanned Ground Vehicles, Project DV7 Small Unmanned Ground Vehicle to PE604017A Robotics Development, Project FD9 Robotics Systems.

A. Mission Description and Budget Item Justification

Soldier Robotics Systems for Robotics Development (RD) includes efforts necessary to evaluate integrated technologies, validate materiel solutions, pre-materiel development decision activities in support of Analysis of Alternatives (AoA) activities for emerging requirements and programs of record. RD is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects, REP initiatives and/or Small Business Innovative Research (SBIR) into emerging programs of record through development of emerging capabilities. This line is for robotic systems that are transported by individual Soldiers and vehicles. RD supports early evaluations for operational effectiveness studies of platforms (i.e. Common Robotics System (Vehicle) (CRS(V)), Common Robotics System (Individual) (CRS(I)), Light Reconnaissance Robot (LRR), Short Range Micro (SRM), Common Robotics System (Heavy) (CRS(H)), Explosive Ordnance Disposal Robotics Payload (ERP) and Chemical, Biological, Radiological, and Nuclear (CBRN)) to determine Technology Readiness Levels (TRL) and Manufacturing Readiness Levels (MRL). Studies support AoA that include Army Materiel Systems Analysis Activity (AMSAA), RAND Corporation studies, and/or modeling to increase confidence in the materiel solution defined in the emerging Capability Development Document (CDD)/Capability Production Document (CPD) that support appropriate Acquisition Category (ACAT), Milestone Decision Authority (MDA) and office of primary responsibility designations. This line also covers pre-acquisition activities intended to reduce risk of not fielding capabilities by the required date, such as market surveys, technical risk assessments, initial development of performance specifications, scopes of work, acquisition strategies, systems engineering plans, test & evaluation master plans, lifecycle sustainment plans, early test planning activities, and prototype development activities.

The Battery Modernization & Interface Standardization (BMIS) program was established to help bring greater power efficiency and effectiveness to the dismounted Soldier, and to reduce the proliferation of proprietary batteries across the Army. BMIS will develop the Army Standard Family of Batteries (SFoB,), a central acquisition management authority, and reduce 38 Communications-Electronics (C-E) battery types, currently in use, to just three. Battery standardization and policy enforcement will support Operational Readiness at a reduced cost to the Army while maintaining configuration management, life cycle support, safety standards, and technological upgrades.

Exhibit R-2, RDT&E Budget Item Justification: FY 2018 Army

Date: May 2017

Appropriation/Budget Activity

2040: Research, Development, Test & Evaluation, Army I BA 4: Advanced Component Development & Prototypes (ACD&P)

R-1 Program Element (Number/Name)
PE 0604017A / Robotics Development

Robotics Systems for Applique and Large Unmanned Ground Systems (ALUGS) Robotics Development (RD) includes efforts necessary to evaluate integrated technologies, validate materiel solutions and determine initial studies and analyses in support of pre-materiel development decision activities for emerging requirements and programs of record. RD is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects, and/ or Small Business Innovative Research (SBIR) into emerging programs of record through development of emerging capabilities. This line is for robotic systems that are transported by vehicle, maneuver under their own power, or are installed as robotic applique kits. RD supports early evaluations for operational effectiveness studies of platforms (i.e. Leader/ Follower (LF), Automated Convoy Operations (ACO), Route Clearance & Interrogation System (RCIS) Type II, Robotic Wingman, etc.) to determine Technology Readiness Levels (TRL) and Manufacturing Readiness Levels (MRL). Studies support Analysis of Alternatives (AoA) that include Army Materiel Systems Analysis Activity (AMSAA), RAND studies, and/or modeling to increase confidence in the materiel solution defined in the emerging Capability Development Document (CDD)/Capability Production Document (CPD) that support appropriate Acquisition Category (ACAT), Milestone Decision Authority (MDA) and office of primary responsibility designations. This line also covers pre-acquisition activities intended to reduce risk of not fielding capabilities by the required date, such as market surveys, technical risk assessments, initial development of performance specifications, scopes of work, acquisition strategies, systems engineering plans, test & evaluation master plans, lifecycle sustainment plans, early test planning activities, and prototype development activities. Product Manager ALUGS will lead the development of a LF Software Integration Lab (SIL), in addition to Modeling and Simulation (M&S) effo

Leader Follower will provide a limited autonomous vehicle capability to the Palletized Load System (PLS) A1. Leader Follower will provide capability for a manned Leader vehicle with up to seven (7) unmanned Follower vehicles. Initial efforts by the United States Army Tank Automotive Research, Development and Engineering Center (TARDEC) will control up to three (3) optionally manned Follower vehicles with a designated Leader vehicle. The manned Leader vehicle wirelessly provides direction and speed guidance to the Follower vehicles to follow the Leader vehicle with no driver input or unmanned. The primary purposes for Leader Follower are to improve Force Protection and increase Logistics Throughput. Funding allows the Army to demonstrate and operationally assess an unmanned vehicle capability with operational units and users to validate the technology.

B. Program Change Summary (\$ in Millions)	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Previous President's Budget	0.000	0.000	0.000	-	0.000
Current President's Budget	0.000	0.000	39.608	-	39.608
Total Adjustments	0.000	0.000	39.608	-	39.608
 Congressional General Reductions 	-	-			
 Congressional Directed Reductions 	-	-			
 Congressional Rescissions 	-	-			
 Congressional Adds 	-	-			
 Congressional Directed Transfers 	-	-			
 Reprogrammings 	-	-			
SBIR/STTR Transfer	-	-			
Adjustments to Budget Years	0.000	0.000	39.608	-	39.608

PE 0604017A: Robotics Development

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Exhibit R-2, RDT&E Budget Item Justification: FY 2018 Army		Date: May 2017
Appropriation/Budget Activity 2040: Research, Development, Test & Evaluation, Army I BA 4: Advanced Component Development & Prototypes (ACD&P)	R-1 Program Element (Number/Name) PE 0604017A I Robotics Development	,
Change Summary Explanation In FY2018 funding for Unmanned Ground Vehicles (UGV) Robotics De Project DV7 Small Unmanned Ground Vehicle to PE 0604017A Robot Large Unmanned Ground Systems (ALUGS) Robotics Development (Unmanned Ground Vehicle to PE604017A Robotics Development, Programment (Unmanned Ground Vehicle to PE604017A Robotics Development, Programment)	tics Development, Project FD2 Soldier Robotics (RD) transitions from PE 0604641A Tactical Unm	Systems, and funding for Applique and

Exhibit R-2A, RDT&E Project Justification: FY 2018 Army											2017		
Appropriation/Budget Activity 2040 / 4						, , , , ,					lumber/Name) dier Robotics Systems		
COST (\$ in Millions)	Prior Years	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total	FY 2019	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cost	
FD2: Soldier Robotics Systems	-	0.000	0.000	1.512	-	1.512	2.812	3.728	4.254	4.251	0.000	16.557	
Quantity of RDT&E Articles	-	-	-	-	-	-	-	-	-	-			

Note

In FY2018 funding for Unmanned Ground Vehicle (UGV) Robotics Development (RD) will transition from PE 0604641A Tactical Unmanned Ground Vehicle, Project DV7 Small Unmanned Ground Vehicle to PE 0604017A Robotics Development, Project FD2 Soldier Robotics Systems.

A. Mission Description and Budget Item Justification

Soldier Robotics Systems for Robotics Development (RD) includes efforts necessary to evaluate integrated technologies, validate materiel solutions, pre-materiel development decision activities in support of Analysis of Alternatives (AoA) activities for emerging requirements and programs of record. RD is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects, Robotic Enhanced Program (REP) initiatives and/or Small Business Innovative Research (SBIR) into emerging programs of record through development of emerging capabilities. This line is for robotic systems that are transported by individual Soldiers and vehicles. RD supports early evaluations for operational effectiveness studies of platforms (i.e. Common Robotics System (Vehicle) (CRS(V)), Common Robotics System (Individual) (CRS(I)), Light Reconnaissance Robot (LRR), Short Range Micro (SRM), Common Robotics System (Heavy) (CRS(H)), Explosive Ordnance Disposal Robotics Payload (ERP) and Chemical, Biological, Radiological, and Nuclear (CBRN)) to determine Technology Readiness Levels (TRL) and Manufacturing Readiness Levels (MRL). Studies support AoA that include Army Materiel Systems Analysis Activity (AMSAA), RAND Corporation studies, and/or modeling to increase confidence in the materiel solution defined in the emerging Capability Development Document (CDD)/Capability Production Document (CPD) that support appropriate Acquisition Category (ACAT), Milestone Decision Authority (MDA) and office of primary responsibility designations. This line also covers pre-acquisition activities intended to reduce risk of not fielding capabilities by the required date, such as market surveys, technical risk assessments, initial development of performance specifications, scopes of work, acquisition strategies, systems engineering plans, test & evaluation master plans, lifecycle sustainment plans, early test planning activities, and prototype development activities.

B. Accomplishments/Planned Programs (\$ in Millions)			FY 2018	FY 2018	FY 2018
	FY 2016	FY 2017	Base	OCO	Total
Title: Soldier Robotics Development	-	-	0.344	-	0.344
Description: Soldier Robotics Development is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects into emerging programs of record. It informs the acquisition process beforehand allowing the Maneuver Center of Excellence (MCoE) the ability to make integration decisions and affordability trades while writing requirements.					
FY 2018 Base Plans:					

PE 0604017A: Robotics Development

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Exhibit R-2A, RDT&E Project Jus	tification: FY	2018 Army							Date: May	/ 2017	
Appropriation/Budget Activity 2040 / 4					•	n ent (Numb botics Devel		t (Number/Name) Soldier Robotics Systems			
B. Accomplishments/Planned Pro	ograms (\$ in N	<u>/lillions)</u>					FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Develop initial program cost estima initiate Request for Proposal (RFP)					Alternatives	(AoA), and					
Title: UGV Robotics Development							-	-	1.168	-	1.16
Description: UGV Robotics Develor Ordnance Disposal Robotic Payloa autonomy and mapping. FY 2018 Base Plans: Robotics Development is designed from science and technology (S&T) beforehand allowing key stakeholde writing requirements. Develop initia	d (ERP), and (to facilitate the projects into ears the ability t	Chemical, Bi e transition o emerging pro o make integ	ological, Rad of robotics an ograms of re- gration decis	diological, ar ad autonomo cord. It inforr ions and affo	nd Nuclear (for substance of the systems of the acquired or the acquired or the system of the system	CBRN) technology sition proces des while	ss				
Alternatives (AoA), and initiate Req		sal (RFP) w	ork for incorp	oration into	the CDD/CF	PD.					
Alternatives (AoA), and initiate Req		sal (RFP) w		oration into	the CDD/CF	PD.	ıls -	-	1.512	2 -	1.51
Alternatives (AoA), and initiate Req C. Other Program Funding Summ	uest for Propo	sal (RFP) w	ork for incorp	oration into	the CDD/CF	PD.	ıls -	-	1.512	2 -	1.51
C. Other Program Funding Summ	uest for Propo	sal (RFP) we	ork for incorp Accomplish FY 2018	poration into nments/Plar FY 2018	the CDD/CF	PĎ. I ms Subtot a	I			Cost To	
C. Other Program Funding Summ Line Item	uest for Propo nary (\$ in Milli FY 2016	sal (RFP) we ons) FY 2017	ork for incorp Accomplish FY 2018 Base	ooration into nments/Plar	the CDD/CF nned Progra FY 2018 Total	PĎ. Ims Subtota FY 2019	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cos
C. Other Program Funding Summ Line Item • 603774A - Night Vision	uest for Propo	sal (RFP) we	ork for incorp Accomplish FY 2018	poration into nments/Plar FY 2018	the CDD/CF	PĎ. I ms Subtot a	I		FY 2022	Cost To	Total Cos
C. Other Program Funding Summ Line Item	uest for Propo nary (\$ in Milli FY 2016	sal (RFP) we ons) FY 2017	ork for incorp Accomplish FY 2018 Base	poration into nments/Plar FY 2018	the CDD/CF nned Progra FY 2018 Total	PĎ. Ims Subtota FY 2019	FY 2020	FY 2021	FY 2022 7.451	Cost To Complete	Total Cos Continuin
C. Other Program Funding Summ Line Item • 603774A - Night Vision Systems Adva: VT7 • 0604710A - Night	nary (\$ in Milli FY 2016 7.003	ons) FY 2017 10.321	FY 2018 Base 12.347	poration into nments/Plar FY 2018	FY 2018 Total 12.347	PD. Ims Subtota FY 2019 8.435	FY 2020 6.779	FY 2021 6.828	FY 2022 7.451 19.200	Cost To Complete Continuing	Total Cos Continuin
Line Item • 603774A - Night Vision Systems Adva: VT7 • 0604710A - Night Vision Systems - E: L67 • Helmet Mounted Enhanced	rest for Propo mary (\$ in Milli FY 2016 7.003 19.710	ons) FY 2017 10.321 26.257	FY 2018 Base 12.347 32.504	Propertion into the properties of the properties	FY 2018 Total 12.347 32.504	FY 2019 8.435 23.355	FY 2020 6.779 19.649	FY 2021 6.828 19.343	FY 2022 7.451 19.200 33.076	Cost To Complete Continuing	Total Cos Continuin Continuin
Line Item • 603774A - Night Vision Systems Adva: VT7 • 0604710A - Night Vision Systems - E: L67 • Helmet Mounted Enhanced Vision Devi: (SSN K36400) • Family of Weapons Sights	nary (\$ in Milli FY 2016 7.003 19.710 97.777	ons) FY 2017 10.321 26.257 156.197	FY 2018 Base 12.347 32.504 144.617	Propertion into the properties of the properties	FY 2018	FY 2019 8.435 23.355 120.898	FY 2020 6.779 19.649 91.640	FY 2021 6.828 19.343 43.111	FY 2022 7.451 19.200 33.076 19.900	Cost To Complete Continuing Continuing Continuing	Total Cos Continuin Continuin Continuin
Line Item • 603774A - Night Vision Systems Adva: VT7 • 0604710A - Night Vision Systems - E: L67 • Helmet Mounted Enhanced Vision Devi: (SSN K36400) • Family of Weapons Sights - Inidivid: (SSN K22002) • Family of Weapons Sights	nary (\$ in Milli FY 2016 7.003 19.710 97.777	ons) FY 2017 10.321 26.257 156.197	FY 2018 Base 12.347 32.504 144.617 49.887	Propertion into the properties of the properties	FY 2018 Total 12.347 32.504 144.644 49.887	FY 2019 8.435 23.355 120.898 89.769	FY 2020 6.779 19.649 91.640 83.246	FY 2021 6.828 19.343 43.111 80.685	FY 2022 7.451 19.200 33.076 19.900 95.575	Cost To Complete Continuing Continuing Continuing Continuing	Continuin Continuin Continuin Continuin Continuin

PE 0604017A: Robotics Development

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Exhibit R-2A, RDT&E Project Justification: FY 2018 An	my	Date : May 2017
Appropriation/Budget Activity 2040 / 4	R-1 Program Element (Number/Name) PE 0604017A / Robotics Development	Project (Number/Name) FD2 / Soldier Robotics Systems
D. Acquisition Strategy	TE 00040 TTAT ROBORIOS BOVOLOPINEIR	1 B2 1 Coluier Resource Cystems
N/A		
E. Performance Metrics		
N/A		

Exhibit R-2A, RDT&E Project J	ustification	: FY 2018 A	rmy							Date: May	2017		
Appropriation/Budget Activity 2040 / 4	•					, , ,					Number/Name) ttery Modernization & Interface ization		
COST (\$ in Millions)	Prior Years	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total	FY 2019	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cost	
FD3: Battery Modernization & Interface Standardization	-	0.000	0.000	0.847	-	0.847	0.858	0.000	0.000	0.000	0.000	1.705	
Quantity of RDT&E Articles	_	-	-	-	-	-	-	-	-	-			

Note

This project is a new start in FY 2018.

A. Mission Description and Budget Item Justification

The Battery Modernization & Interface Standardization (BMIS) program was established to help bring greater power efficiency and effectiveness to the dismounted Soldier, and to reduce the proliferation of proprietary batteries across the Army. BMIS will develop the Army Standard Family of Batteries (SFoB,), a central acquisition management authority, and reduce 38 Communications-Electronics (C-E) battery types, currently in use, to just three. Battery standardization and policy enforcement will support Operational Readiness at a reduced cost to the Army while maintaining configuration management, life cycle support, safety standards, and technological upgrades.

B. Accomplishments/Planned Programs (\$ in Millions)	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Title: Acquisition Strategy	-	-	0.212	-	0.212
Description: Complete advanced development pre-milestone B assessments and analysis.					
FY 2018 Base Plans: Complete advanced development pre-milestone B technology assessments and analysis. Conduct C-E battery market Research/Requests for Information (RFI). Develop Acquisition Strategy and Requests for Proposals (RFPs)					
Title: BMIS Standard Family of Batteries (SFoB) Design	-	-	0.635	-	0.635
Description: Conduct research and complete assessment of technology and portfolios. Establish a foundation for the development and usage of prototypes. Once the SFoB has been established, maintenance and updates will be made as technology advances.					
FY 2018 Base Plans:					

PE 0604017A: Robotics Development

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Exhibit R-2A, RDT&E Project Justification: FY 2018 Army			Date: May 2017
Appropriation/Budget Activity 2040 / 4	R-1 Program Element (Number/Name) PE 0604017A / Robotics Development	- 3 (umber/Name) ery Modernization & Interface ation

B. Accomplishments/Planned Programs (\$ in Millions)	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Assess the current C-E Battery Portfolio. Complete the C-E Battery technology assessment. Determine a solid and integrated core Standard Family of Batteries that will align with the BMIS mission. Prepare solicitation for development of advanced prototype requirements for C-E batteries.					
Accomplishments/Planned Programs Subtotals	-	-	0.847	-	0.847

C. Other Program Funding Summary (\$ in Millions)

N/A

Remarks

D. Acquisition Strategy

BMIS will leverage full and open competition to award a contract for the engineering and development of the Army Standard Family of Batteries.

E. Performance Metrics

N/A

PE 0604017A: *Robotics Development* Army

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Exhibit R-2A, RDT&E Project Ju	stification	: FY 2018 A	rmy							Date: May 2017			
Appropriation/Budget Activity 2040 / 4						, , , , , , , , , , , , , , , , , , , ,					Number/Name) botics Systems		
COST (\$ in Millions)	Prior Years	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total	FY 2019	FY 2020	FY 2021	FY 2022	Cost To Complete	Total Cost	
FD9: Robotics Systems	-	0.000	0.000	37.249	-	37.249	65.400	13.000	13.000	3.000	Continuing	Continuing	
Quantity of RDT&E Articles	-	-	-	-	-	-	-	-	-	-			

Note

In FY2018, funding for Applique and Large Unmanned Ground Systems (ALUGS) Robotics Development transitions from PE 0604641A Tactical Unmanned Ground Vehicles to PE604017A Robotics Development, Project FD9 Robotics Systems.

A. Mission Description and Budget Item Justification

Robotics Systems for Applique and Large Unmanned Ground Systems (ALUGS) Robotics Development (RD) includes efforts necessary to evaluate integrated technologies, validate materiel solutions and determine initial studies and analyses in support of pre-materiel development decision activities for emerging requirements and Programs of Record. RD is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects, and/or Small Business Innovative Research (SBIR) into emerging programs of record through development of emerging capabilities. This line is for robotic systems that are transported by vehicle, maneuver under their own power, or are installed as robotic applique kits. RD supports early evaluations for operational effectiveness studies of platforms (i.e. Leader Follower (LF), Automated Convoy Operations (ACO), Route Clearance & Interrogation System (RCIS) Type II, Robotic Wingman (RW), etc.) to determine Technology Readiness Levels (TRL) and Manufacturing Readiness Levels (MRL). Studies support Analysis of Alternatives (AoA) that include Army Materiel Systems Analysis Activity (AMSAA), RAND studies, and/or modeling to increase confidence in the materiel solution defined in the emerging Capability Development Document (CDD)/Capability Production Document (CPD) that support appropriate Acquisition Category (ACAT), Milestone Decision Authority (MDA) and office of primary responsibility designations. This line also covers pre-acquisition activities intended to reduce risk of not fielding capabilities by the required date, such as market surveys, technical risk assessments, initial development of performance specifications, scopes of work, acquisition strategies, systems engineering plans, test & evaluation master plans, lifecycle sustainment plans, early test planning activities, and prototype development activities. The Army Tank Automotive Research Development and Engineering Center (TARDEC) will build, and test prototype LF systems for safety rel

Leader Follower (LF) will provide a limited autonomous vehicle capability to the Palletized Load System (PLS) A1. Leader Follower will provide capability for a manned Leader vehicle with up to seven (7) unmanned Follower vehicles. Initial efforts by the United States Army Tank Automotive Research, Development and Engineering Center will control up to three (3) optionally manned Follower vehicles with a designated Leader vehicle. The manned Leader vehicle wirelessly provides direction and speed guidance to the Follower vehicles to follow the Leader vehicle with no driver input or unmanned. The primary purposes for Leader Follower are to improve Force Protection and increase Logistics Throughput. Funding allows the Army to demonstrate and operationally assess an unmanned vehicle capability with operational units and users to validate the technology.

B. Accomplishments/Planned Programs (\$ in Millions)	FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Title: Leader Follower (LF) - PdM Applique & Large Unmanned Ground Systems (ALUGS)	-	-	6.264	-	6.264

UI	NCLASSIFIED					
Exhibit R-2A, RDT&E Project Justification: FY 2018 Army				Date: May	2017	
Appropriation/Budget Activity 2040 / 4	R-1 Program Element (Number/ PE 0604017A / Robotics Develop			umber/Nan otics Systen		
B. Accomplishments/Planned Programs (\$ in Millions)		FY 2016	FY 2017	FY 2018 Base	FY 2018 OCO	FY 2018 Total
Description: Leader Follower (LF) Program in PdM ALUGS builds upon the Tollower Excursion to Development & Engineering Center (TARDEC) Leader Follower Excursion to vehicle capability to the Palletized Load System (PLS) A1. Current PdM effort Program of Record capability, expanding the TARDEC efforts to include up to vehicles. Funding will Recap ten (10) PLS trucks for testing purposes while the through the TARDEC effort. Other efforts include Capabilities Document input activities that feed cost estimates, capturing technical data, test data, test sup Simulation (M&S) use cases and development of a Software Integration Lab (provide a limited autonomous s will lay the groundwork for future seven (7) unmanned Follower he applique kits are procured t, close monitoring of Excursion port, developing Modeling and					
FY 2018 Base Plans: Funding supports attaining Recapitalized Palletized Load System (PLS) vehicle assets in support of the TARDEC Leader Follower Excursion applique kit pure vehicles; plus it funds follow on Program of Record technology insertions, technology development and Initial prototype testing will refine the system performa	chase and install on these test noology transition and testing.					
follower system capabilities. Development of a Software Integration Lab (SIL) Simulation (M&S) efforts that will stress the Leader Follower systems and ultir testing requirements and costs through validated simulations.), in addition to Modeling and					
Title: Robotic Wingman (RW)/Automated Convoy Operations (ACO)		-	-	0.985	-	0.985
Description: Robotic Wingman (RW) is a lethal ground vehicle system control vehicle in close proximity. Automated Convoy Operations (ACO) is an advance and vehicle by-wire control hardware and software, designed to retrofit robotic heavy legacy Tactical Wheeled Vehicle Fleets. Robotics Development funding Science and Technology (S&T) projects/demonstrations into program of record	ed modular kit made of sensors c capabilities onto both medium and ng helps transition RW/ACO from					
FY 2018 Base Plans: FY 2018 funding supports Systems Engineering, Requirements, Cost Analysis	s, and technology transition plans.					
Title: Leader Follower - Tank Automotive Research Development & Engineer	ing Center (TARDEC) Excursion	-	-	30.000	-	30.000
Description: Leader Follower provides a limited autonomous vehicle software ALUGS test Palletized Load System (PLS) A1s. For the TARDEC Excursion, a designated manned Leader vehicle which leads a line of three (3) optionally The Leader vehicle wirelessly provides directional and speed guidance to the	the applique kit provides manned Follower vehicles.					

PE 0604017A: *Robotics Development* Army

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Exhibit R-2A, RDT&E Project Justification: FY 2018 Army		Date: May 2017
	` ' '	lumber/Name) otics Systems

B. Accomplishments/Flanned Frograms (\$ in Millions)			1 1 2010	1 1 2010	1 1 2010
	FY 2016	FY 2017	Base	oco	Total
Leader vehicle with no driver input or unmanned. The primary purposes for Leader Follower is to improve Force					
Protection and increase logistics throughput. Funding allows the Army to demonstrate and operationally assess					
an unmanned vehicle capability with operational units and users to validate the technology. The Army will build,					
and test prototype systems for safety release, Soldier use, and further technology maturation.					
FY 2018 Base Plans:					
FY 2018 funding allows the maturation and build of ten (10) Applique initial prototype Leader Follower systems					
for testing and safety assessment, applied to the ALUGS acquired ten (10) PLS A1 test vehicles. The					
prototypes will integrate a by-wire kit to the existing tactical vehicle to enable remote operation of steering,					
braking, throttle control and other functions. An autonomy kit will also enable the platforms to operate in					
leader/follower mode by providing sensor information and control algorithms to control the by-wire kit. M&S					
development and Initial prototype testing will refine the system performance to meet required leader follower					
system capabilities. In addition, the funding initiates long lead item purchases for up to one hundred and forty					
(140) Applique systems for user operational assessment, testing, and development planned in FY19 and FY20					
on additional PLS trucks in FORSCOM identified units.					
Accomplishments/Planned Programs Subtotals	-	-	37.249	-	37.249

C. Other Program Funding Summary (\$ in Millions)

B. Accomplishments/Planned Programs (\$ in Millions)

N/A

Army

Remarks

D. Acquisition Strategy

Robotics Development (RD) is designed to facilitate the transition of robotics and autonomous systems technology from Science and Technology (S&T) projects into emerging programs of record. It informs the acquisition process beforehand allowing key stakeholders the ability to make integration decisions and affordability trades while writing requirements.

Tank Automotive Armaments Research Development & Engineering Center (TARDEC) funding allows the Army to demonstrate and operationally assess an unmanned vehicle capability with operational units and users to validate the technology. The Army will build, and test prototype systems for safety release, Soldier use, and further technology maturation.

Product Manager Applique and Large Unmanned Ground Systems (PdM ALUGS) builds upon the TARDEC Leader Follower (LF) Excursion to provide a limited autonomous vehicle capability to the Palletized Load System (PLS) A1. Efforts include Capabilities Document input, close monitoring of Excursion activities that feed cost estimates, capturing technical data, test data, test support, developing Modeling and Simulation use cases and development of a Software Integration Lab.

PE 0604017A: Robotics Development

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R-1 Line #69

FY 2018 | FY 2018 | FY 2018

Exhibit R-2A, RDT&E Project Justification: FY 2018 Army		,	Date: May 2017
Appropriation/Budget Activity 2040 / 4	R-1 Program Element (Number/Name) PE 0604017A / Robotics Development		umber/Name) otics Systems
Automated Convoy Operations (ACO)/Robotic Wingman (RW) FY 2018 funding plans.	g supports Systems Engineering, Requireme	ents, Cost An	alysis, and technology transition
E. Performance Metrics N/A			

Exhibit R-3, RDT&E Project Cost Analysis: FY 2018 Army

Date: May 2017

Appropriation/Budget Activity

2040 / 4

R-1 Program Element (Number/Name)
PE 0604017A / Robotics Development
FD9 / Robotics Systems

Product Developmen	it (\$ in M	illions)		FY 2	2016	FY 2	2017	FY 2 Ba	2018 se	FY 2		FY 2018 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To Complete	Total Cost	Target Value of Contract
Leader Follower Test Assets	MIPR	PdM HTV : Warren, MI	0.000	-		-		4.874	Oct 2017	-		4.874	0.000	4.874	0.000
Leader Follower (TARDEC) excursion A Kit	C/CPFF	Lokheed Martin : Camden, NJ	0.000	-		-		11.000	Apr 2018	-		11.000	0.000	11.000	0.000
Leader Follower (TARDEC) excursion B Kit	C/CPFF	Oshkosh : Oshkosh, WI	0.000	-		-		10.000	Apr 2018	-		10.000	0.000	10.000	0.000
Leader Follower (TARDEC) excursion Integrated System Integrator	C/CPFF	TBD : TBD	0.000	-		-		4.500		-		4.500	0.000	4.500	0.000
Leader Follower (TARDEC) excursion Warfighter Machine Interface	C/CPFF	DCS Corp : Boston, MA	0.000	-		-		2.500		-		2.500	0.000	2.500	0.000
		Subtotal	0.000	-		-		32.874		-		32.874	0.000	32.874	0.000

Remarks

LF Test Assets funding of \$4.874M of the ALUGS \$7M on a MIPR to PdM HTV secures the recap of ten (10) PLS A1s. This funding will be executed on the HTV Recap contract with Oshkosh to support testing and evaluation of Leader Follower solution developed in the Science & Technology TARDEC excursion.

Support (\$ in Million	ıs)			FY 2	2016	FY 2	2017		2018 ise	FY 2		FY 2018 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To Complete	Total Cost	Target Value of Contract
PdM ALUGS Support	MIPR	Various : Multiple locations	0.000	-		-		2.375		-		2.375	0.000	2.375	0.000
TARDEC Excursion support	MIPR	TARDEC : Warren, MI	0.000	-		-		1.000	Oct 2017	-		1.000	0.000	1.000	0.000
		Subtotal	0.000	-		-		3.375		-		3.375	0.000	3.375	0.000

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Exhibit R-3, RDT&E Project Cost Analysis: FY 2018 Army

Appropriation/Budget Activity

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R-1 Program Element (Number/Name)
PE 0604017A / Robotics Development
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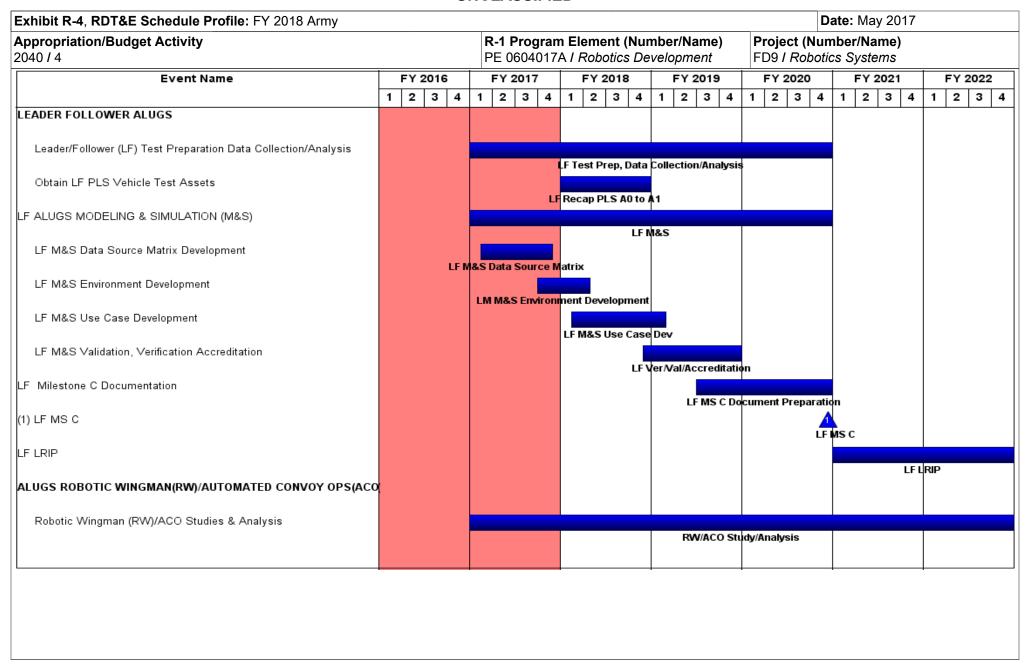
Test and Evaluation	(\$ in Milli	ons)		FY 2	2016	FY 2	2017	FY 2 Ba	2018 ise		2018 CO	FY 2018 Total			
Cost Category Item	Contract Method & Type	Performing Activity & Location	Prior Years	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Award Date	Cost	Cost To Complete	Total Cost	Target Value of Contract
Leader Follower (TARDEC) excursion Testing	MIPR	ATEC : Aberdeen, MD	0.000	-		-		0.500	Jul 2018	-		0.500	0.000	0.500	0.000
Leader Follower (TARDEC) excursion Data Logger	MIPR	ATEC : Aberdeen, MD	0.000	-		-		0.500	Apr 2018	-		0.500	0.000	0.500	0.000
		Subtotal	0.000	-		-		1.000		-		1.000	0.000	1.000	0.000
															Target

	Prior Years	FY 2	2016	FY 2	2017	FY 2 Ba	2018 se		2018 CO	FY 2018 Total	Cost To	Total Cost	Target Value of Contract	- 1
Project Cost Totals	0.000	-		0.000		37.249		-		37.249	0.000	37.249	-	1

Remarks

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xhibit R-4, RDT&E Schedule Profile: FY 2018 Army																					Da	ate	e: N	lay	201	7				
ppropriation/Budget Activity 040 / 4						Prog 06040)					Num ootic									
Event Name	F	FY 20	016		FY	2017	'		FY 2	2018	8		F	Y 20	019)		FY	20	20			F	Y 20	21		F	Y 2	022	:
	1	2	3 4	1	2	3	4	1	2	3	4	1	П	2	3	4	1	2	: [3	4	1		2	3	4	1	2	3	4
ARDEC LEADER FOLLOWER EXCURSION																														
TARDEC LF Applique Prototype Build (10) for test						Appli	iauo)rote	oteme	o Pui	ild	e Int		ation	. / 10															
TARDEC LF Order Items for 140 Applique Systems						Appii	ique i							(140)		"														
TARDEC LF Contractor Engineering Test								Lon	ig Le			acto																		
ATEC LF Urgent Material Release (UMR) & Safety Test (TARDEC)										C	ond	acto		csi	Δ.	TEC	tos													
TARDEC LF Applique Build (140) for Excursion										Rui	ild E		reio	n Ap					(14	ını										
(1) TARDEC LF Urgent Material Release (UMR)										Dui	iiu E	7	SIC	лі Ар	piiq	ue s	DIMI		(14	10)										
(2) TARDEC LF First Unit of Issue																	Δ	` •												
TARDEC LF Excursion Assessment															_															
															ы	valua	ite L	.FS)	/ste	ems	in F	DRS	SCC)M u	nıts					
												•					•									•				

Exhibit R-4A, RDT&E Schedule Details: FY 2018 Army			Date: May 2017
Appropriation/Budget Activity	R-1 Program Element (Number/Name)	Project (N	umber/Name)
2040 / 4	PE 0604017A I Robotics Development	FD9 / Robo	otics Systems

Schedule Details

	Sta	art	Eı	nd
Events	Quarter	Year	Quarter	Year
LEADER FOLLOWER ALUGS	1	2017	4	2022
Leader/Follower (LF) Test Preparation Data Collection/Analysis	1	2017	4	2020
Obtain LF PLS Vehicle Test Assets	1	2018	4	2018
LF ALUGS MODELING & SIMULATION (M&S)	1	2017	4	2020
LF M&S Data Source Matrix Development	1	2017	4	2017
LF M&S Environment Development	4	2017	2	2018
LF M&S Use Case Development	1	2018	1	2019
LF M&S Validation, Verification Accreditation	4	2018	4	2019
LF Milestone C Documentation	3	2019	4	2020
LF MS C	4	2020	4	2020
LF LRIP	1	2021	1	2024
ALUGS ROBOTIC WINGMAN(RW)/AUTOMATED CONVOY OPS(ACO)	1	2017	4	2022
Robotic Wingman (RW)/ACO Studies & Analysis	1	2017	4	2022
TARDEC LEADER FOLLOWER EXCURSION	3	2018	3	2022
TARDEC LF Applique Prototype Build (10) for test	3	2018	4	2018
TARDEC LF Order Items for 140 Applique Systems	3	2018	4	2018
TARDEC LF Contractor Engineering Test	3	2018	2	2019
ATEC LF Urgent Material Release (UMR) & Safety Test (TARDEC)	2	2019	3	2020
TARDEC LF Applique Build (140) for Excursion	2	2019	4	2019
TARDEC LF Urgent Material Release (UMR)	1	2020	1	2020
TARDEC LF First Unit of Issue	1	2020	1	2020
TARDEC LF Excursion Assessment	1	2020	2	2021

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