ARMY RDT&E BUDGET IT	EM JU	STIFI	CATIO	N (R-2	Exhibi	it)	Fe	ebruary 2	003	
BUDGET ACTIVITY 5 - System Development and Demonstration		(E NUMBER)604778A (SPACE)			ms Devel	opment		PROJECT 168	
COST (In Thousands)	FY 2002 Actual	FY 2003 Estimate	FY 2004 Estimate	FY 2005 Estimate	FY 2006 Estimate	FY 2007 Estimate	FY 2008 Estimate	FY 2009 Estimate	Cost to Complete	Total Cost
168 NAVSTAR GPS EQUIP	0	0	1574	2065	2254	0	0	0	0	8220

A. Mission Description and Budget Item Justification: The Navstar Global Positioning System (Navstar GPS) is a passive, space-based, radio positioning and navigation system providing precise, three dimensional position, navigation, velocity and timing information to warfighters. The Navstar GPS program is designated as a DoD Space Program and the United States Air Force (USAF) is the executive agent. The USAF develops GPS User Equipment (PE 35164F) at the GPS Joint Program Office (JPO) with Army participation. NAVSTAR GPS is composed of three segments: Space, Control, and User Equipment. Project 168 provides for initial and sustained participation in the research and development of Army unique requirements that enhance the Position Navigation capabilities of Army weapons systems and platforms. These funds will be used to increase the functionality and performance of GPS receivers.

This is a Legacy-to-Objective capability supporting all axes of the Army Transformation Campaign.

FY04/FY05 funding provides for the development, demonstration and transition of Urban Situational Awareness elements. These elements will allow the Defense Advanced GPS Receiver (DAGR) to provide more secure and more reliable position and navigation data for the Objective Force.

Accomplishments/Planned Program	FY 2002	FY 2003	FY 2004	FY 2005
Leverage, demonstrate, and transition of Urban Situational Awareness improvements and solutions into Defense Advanced GPS Receiver	0	0	1574	2065
(DAGR) functionality.				
Totals	0	0	1574	2065

	` ,	February 2003
5 - System Development and Demonstration 060	NUMBER AND TITLE 604778A - Positioning Systems Develo 6PACE)	PROJECT 168

B. Program Change Summary	FY 2002	FY 2003	FY 2004	FY 2005
Previous President's Budget (FY 2003)	0	0	0	0
Current Budget (FY 2004/2005 PB)	0	0	1574	2065
Total Adjustments	0	0	1574	2065
Congressional program reductions				
Congressional rescissions				
Congressional increases				
Reprogrammings				
SBIR/STTR Transfer				
Adjustments to Budget Years			1574	2065

Change Summary Explanation:

FY-04 +\$1.6M Funds realigned to support Army Unique GPS Requirements for Urban Situational Awareness efforts.

FY-05 +\$2.1M Funds realigned to support Army Unique GPS Requirements for Urban Situational Awareness efforts.

C. Other Program Funding Summary	FY 2002	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009	To Compl	Total Cost
K47800, Other Procurement, Army, NAVSTAR GPS DAGR	19661	26767	44290	39616	42334	37919	25019	26969	264000	526575

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<u>D. Acquisition Strategy:</u> Leverage commercial technology investment enhance DAGR functionality to include unique Army requirements for position data deep inside buildings, tunnels and caves. This leveraging platform. This contractor is being selected on a competitive basis.	time of arrival augmentation, GPS reception in a low signal	environment, and providing GPS referenced

Method & Location PYs Cost Cost Award Date Date Date Date Cost Award Complete Cost Vi Cot Date Date Date Date Date Date Date Dat		ARM	Y RDT&E CO	ST AN	ALYS	SIS(R-3)			Febi	ruary 200	13	
Method & Type a . Develop P-Code algorithms to support Urban Situational Awareness B . Integrate P-Code algorithms into DAGR product line TBS TBS TBS TBS TBS TBS TBS TB		nent and D	emonstration					g Systems	Develop	oment (SF	PACE)		T
algorithms to support Urban Situational Awareness D. Integrate P-Code algorithms into DAGR product line TBS TBS TBS O O TBS TBS TBS TB	. Product Development	Method &	Performing Activity & Location			Award		Award		Award			Targe Value of Contrac
algorithms into DAGR product line Insupport Cost Contract Method & Location Pry Cost	algorithms to support Urban			0	C		300	1Q	300	1Q	Continue	600	(
Subtotal: Subtot	algorithms into DAGR	TBS	TBS	0	С		874	1Q	1765	1Q	0	2639	(
Method & Location PYs Cost Cost Award Cost Award Cost Award Complete Cost Variable Type 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Subtotal:			0	C		1174		2065		Continue	3239	(
Method & Location PYs Cost Cost Award Cost Award Complete Cost Variable Type Cost Date Date Date Award Complete Cost Variable Cost Award Complete Cost Variable Cost Date Date Date Date Cost Cost Award Complete Cost Variable Cost Date Date Date Date Cost Cost Date Date Date Date Date Date Date Dat													
a . Field/integrate new 0 0 0 0 0 0 0	I. Support Cost	Method &		Total PYs Cost		Award		Award		Award			Targer Value of Contrac
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Subtotal: Image: Control of the control o	Subtotal:			0	C		0		0		0	0	(

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5 System Developin	iciit unu Di			000	J47702 1	ositioning	5 bystems	Бечегор	ment (B1	nel)	100	
III. Test and Evaluation	Contract Method & Type	Performing Activity & Location	Total PYs Cost	FY 2003 Cost	FY 2003 Award Date	FY 2004 Cost	FY 2004 Award Date	FY 2005 Cost	FY 2005 Award Date	Cost To Complete	Total Cost	Targe Value o Contra
a . Test/integrate new capabilities	MIPR	RDEC, Fort Monmouth, NJ	0	0		400	2Q	0		0	400	
Subtotal:			0	0		400		0		0	400	
IV. Management Services	Contract Method & Type	Performing Activity & Location	Total PYs Cost	FY 2003 Cost		FY 2004 Cost	FY 2004 Award Date	FY 2005 Cost	FY 2005 Award Date	Cost To Complete	Total Cost	Targ Value (Contra
Subtotal:			0	0		0		0		0	0	
Project Total Cost:			0	0		1574		2065		Continue	3639	

Schedule Profile Do	etaii (K-4a l	Exnibi	t)				Februa	ary 2003	
BUDGET ACTIVITY 5 - System Development and Demonstration			ER AND TIT B A - Posi t	TLE tioning S	ystems D	evelopmo	ent (SPA)	_	ROJECT 168
Schedule Detail	FY 2002	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009	
Adapt commmercial technology			3Q						
Demonstrate concept interface			3Q						
Qualification/Reliability Test			3-4Q						
Develop prototype				3Q					
Demonstrate prototype				4Q					
System Integration					20				